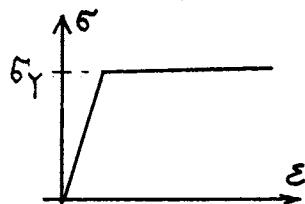


1. Napetostno stanje delca \mathcal{D} je opisano s komponentami σ_{ij} tenzorja napetosti glede na koordinatni sistem (x, y, z) .

- Dokaži, da je ravnina, π_ζ , katere normala e_ζ oklepa enake kote z osmi x, y, z , ena od glavnih ravnin podanega napetostnega stanja! Določi preostali dve glavni ravnini in vse glavne normalne napetosti!
- Določi specifično spremembo prostornine, ki pripada obravnavanemu delcu \mathcal{D} (modul elastičnosti E in koeficient prečne kontrakcije ν sta podani vrednosti)!
- Obravnavano telo je narejeno iz bilinearnega elastično-plastičnega materiala. Pri enoosnem napetostnem stanju je prehod iz elastičnega v plastično stanje določen z mejo plastičnega tečenja σ_Y . Upoštevajoč Misesov pogoj tečenja določi napetost q_Y , pri kateri pri podanem prostorskem napetostnem stanju delca \mathcal{D} nastopijo prve plastične deformacije! Napetost q_Y izrazi v odvisnosti od σ_Y !

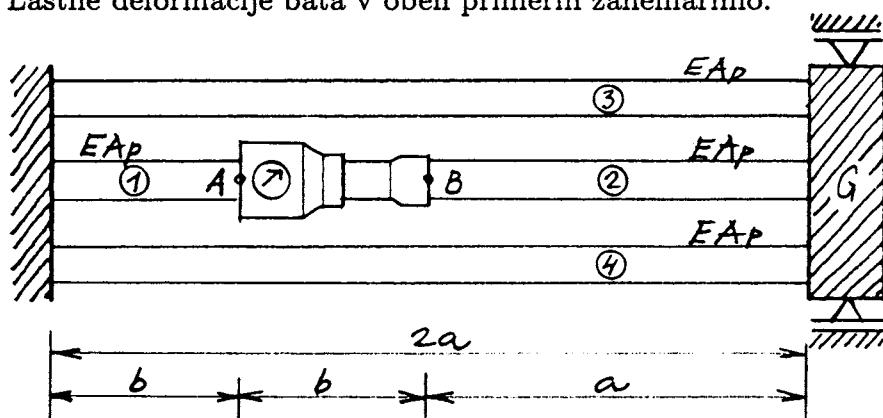


$$[\sigma_{ij}] = \begin{bmatrix} q & 2q & 2q \\ 2q & q & 2q \\ 2q & 2q & q \end{bmatrix}$$

2. Med palici 1 in 2 vstavimo bat hidravlične naprave. V začetku med batom in palicama ni napetosti.

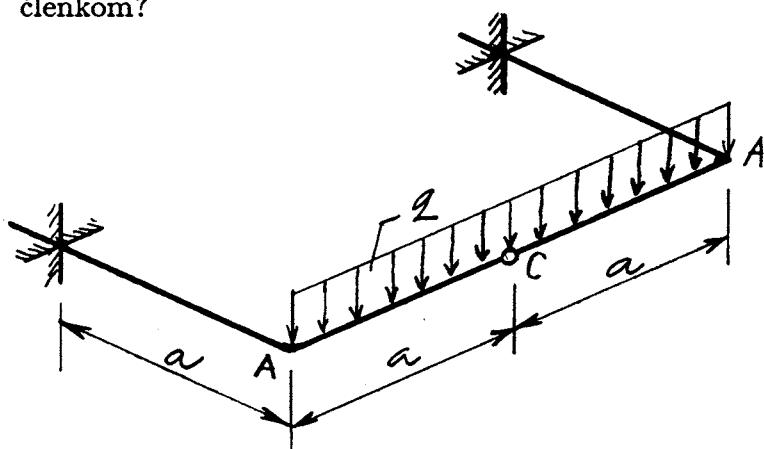
- Določi potrebno silo v batu, pri kateri se razdalja med točkama A in B poveča za $\delta = 2 \text{ mm}$! Kolikšne so tedaj napetosti v palicah?
- Določi potrebno silo v batu, pri kateri se razdalja med točkama A in B ne spremeni, če palici 1 in 2 segrejemo za $\Delta T = 60 \text{ K}$, palici 3 in 4 pa obdržita začetno temperaturo! Določi premik toge vezne grede G!

Lastne deformacije bata v obeh primerih zanemarimo.



$$\begin{aligned} E &= 200\,000 \text{ MPa} \\ \alpha_T &= 1.25 \cdot 10^{-5}/\text{K} \\ a &= 2 \text{ m} \\ b &= 1 \text{ m} \\ A_p &= 10 \text{ cm}^2 \end{aligned}$$

3. Določi navpični pomik točke C! Kako se spremeni ta pomik, če nosilec v točki C ni prekinjen s členkom?



$$\begin{aligned} q &= 0.1 \text{ MN/m} \\ EI_y &= GI_x = 100 \text{ MNm}^2 \\ a &= 3 \text{ m} \end{aligned}$$

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Ad 1.

$$a) \quad e_{fx} = e_{fy} = e_{fz} \rightarrow 3e_{fx}^2 = 1 \rightarrow e_{fx} = \frac{1}{\sqrt{3}}$$

$$\vec{e}_f = \frac{1}{\sqrt{3}} (\vec{e}_x + \vec{e}_y + \vec{e}_z)$$

$$\begin{bmatrix} \tilde{\epsilon}_{fx} \\ \tilde{\epsilon}_{fy} \\ \tilde{\epsilon}_{ fz} \end{bmatrix} = \begin{bmatrix} 2 & 2 & 2 \\ 2 & 2 & 2 \\ 2 & 2 & 2 \end{bmatrix} \cdot \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \frac{5}{\sqrt{3}} \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix}$$

$$\boxed{\tilde{\epsilon}_f = \frac{5}{\sqrt{3}} (\vec{e}_x + \vec{e}_y + \vec{e}_z)}$$

$$\tilde{\epsilon}_{ff} = \tilde{\epsilon}_f \vec{e}_f = \frac{5}{3} (1+1+1) \rightarrow \boxed{\tilde{\epsilon}_{ff} = 5}$$

$$\boxed{\tilde{\epsilon}_f = \tilde{\epsilon}_{ff} \vec{e}_f}$$

$$b) \quad \boxed{\tilde{\epsilon}_{ff} = \tilde{\epsilon}_{33} = 5}$$

$$I_1 = 3$$

$$I_2 = 3 \begin{vmatrix} 2 & 2 \\ 2 & 2 \end{vmatrix} = -9$$

$$I_3 = 2(2^2 - 4^2) - 2(2^2 - 4^2) + 2(4^2 - 2^2)$$

$$I_3 = 5$$

$$\boxed{\tilde{\epsilon}^3 - I_1 \tilde{\epsilon}^2 + I_2 \tilde{\epsilon} - I_3 = 0} \rightarrow$$

$$\tilde{\epsilon}^3 - 3\tilde{\epsilon}^2 - 9\tilde{\epsilon}^2 - 5 = 0$$

$$(5^3 - 3^2 \tilde{\epsilon}^2 - 9^2 \tilde{\epsilon}^2 - 5^3) : (5 - 3) = \tilde{\epsilon}^2 + 2^2 \tilde{\epsilon} + 2^2$$

$$\underline{-5^3 + 5^2 \tilde{\epsilon}^2}$$

$$\underline{2^2 \tilde{\epsilon}^2 - 9^2 \tilde{\epsilon}^2}$$

$$\underline{-2^2 \tilde{\epsilon}^2 + 10^2 \tilde{\epsilon}^2}$$

$$\underline{5^2 - 5^3}$$

$$\sigma^2 + 2\sigma\gamma + \gamma^2 = 0 \rightarrow \boxed{\sigma_{11} = \sigma_{22} = -\gamma}$$

Grama smer $\vec{e}_3 \equiv \vec{e}_5$, grami smeri \vec{e}_1 in \vec{e}_2 sta pravokotni na \vec{e}_5 , zato pa veljata, ker je $\sigma_{11} = \sigma_{22}$!

b) $\boxed{I_1^G = 32}$ $I_1^E \approx E_r = \frac{1-2\gamma}{E} I_1^G$

$$\boxed{E_r = \frac{3(1-2\gamma)}{E} \cdot 2}$$

a) Mises: $(\sigma_{11} - \sigma_{22})^2 + (\sigma_{22} - \sigma_{33})^2 + (\sigma_{33} - \sigma_{11})^2 = 6 k_M^2$

$$\sigma_{22} = \sigma_{33} = 0 \rightarrow 2\sigma_{11}^2 = 6 k_M^2 \rightarrow \sigma_{11}^2 = 3 k_M^2$$

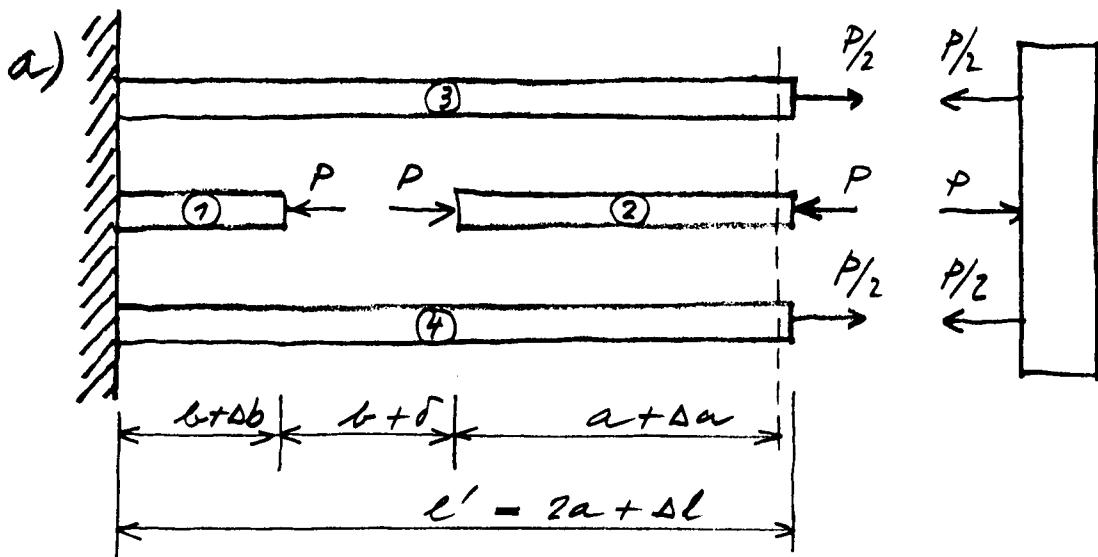
$$\sigma_{11} = \sigma_y \rightarrow \boxed{k_M = \frac{1}{\sqrt{3}} \sigma_y}$$

$$\boxed{(\sigma_{11} - \sigma_{22})^2 + (\sigma_{22} - \sigma_{33})^2 + (\sigma_{33} - \sigma_{11})^2 = 2\sigma_y^2}$$

$$\boxed{\sigma_{11} = \sigma_{22} = -\gamma, \quad \sigma_{33} = 52 :}$$

$$0 + 36\gamma^2 + 36\gamma^2 = 2\sigma_y^2 \rightarrow \boxed{\sigma_y = \frac{1}{6} \sigma_y}$$

Ad 2.)



$$l' = 2a + \frac{P}{2} \cdot \frac{2a}{EA_p} = \left(b - P \frac{b}{EA_p} \right) + \left(a - P \frac{a}{EA_p} \right) + (b + \delta)$$

$$P \frac{1}{EA_p} (a + b + a) = b + a + b + \delta - 2a$$

$$2b + a = 2a \rightarrow P = \frac{\delta EA_p}{2a + b} \rightarrow P = 80 \text{ kN}$$

b) $l' = 2a + \frac{P}{2} \frac{2a}{EA_p} =$
 $= \left(b - P \frac{b}{EA_p} + b \alpha_r \Delta T \right) + \left(a - P \frac{a}{EA_p} + a \alpha_r \Delta T \right) + b$

$$\frac{P}{EA_p} (2a + t) = 2a - 2a + (a + b) \alpha_r \Delta T$$

$$P = \frac{at+b}{2a+b} EA_p \alpha_r \Delta T \rightarrow P = 90 \text{ kN}$$

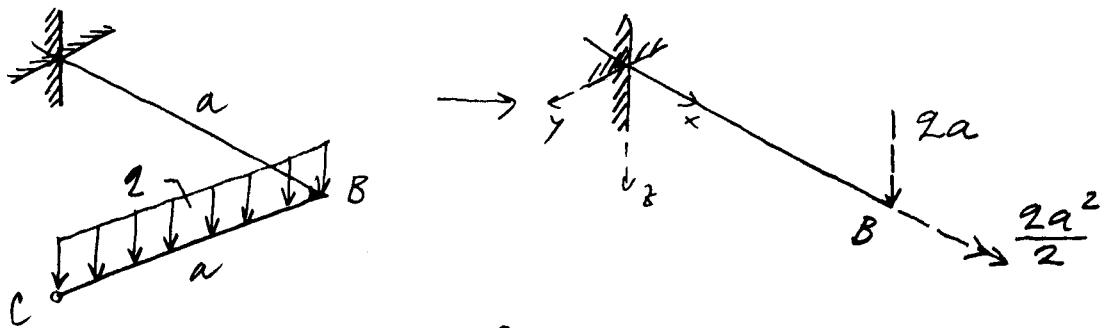
$$u_g = P \frac{a}{EA_p} \rightarrow u_g = 0,09 \text{ cm}$$

a) Nagetastn r' polvcah:

$$\textcircled{1}, \textcircled{2} \rightarrow \boxed{\sigma = -8 \text{ kN/cm}^2} \quad \textcircled{3}, \textcircled{4} \rightarrow \boxed{\sigma = 4 \text{ kN/cm}^2}$$

Ad 3.)

a) členka v trojici C :



$$\omega_x(B) = \frac{2a^2}{2} \cdot \frac{a}{G I_x} = 2 \frac{a^3}{2 G I_x}$$

$$w_B = 2a \frac{a^3}{3 E I_y} = 2 \frac{a^4}{3 E I_y}$$

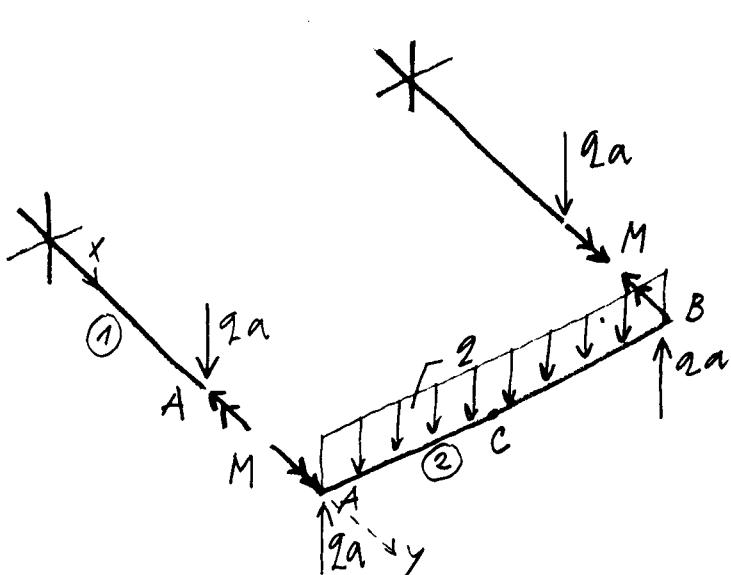
$$w_c = w_B + \omega_x(B) \cdot a + \frac{2a^4}{8 E I_y}$$

$$E I_y = G I_x \rightarrow w_c = \frac{2a^4}{E I_y} \left(\frac{1}{3} + \frac{1}{2} + \frac{1}{8} \right)$$

$$w_c = 2 \frac{23a^4}{24 E I_y}$$

$$w_c = 0,0776 \text{ m}$$

b) bez členky :



$$\textcircled{1}: w_A^{(1)} = 2 \frac{a^4}{3 E I_y}$$

$$\omega_x^{(1)}(A) = \omega_y^{(1)}(A) = -M \frac{a}{G I_x}$$

\textcircled{2}:

$$\omega_y^{(2)}(A) = -2 \frac{(2a)^3}{24 E I_y} + M \frac{2a}{2 E I_y}$$

$$\omega_y^{(2)}(A) = -2 \frac{a^3}{3 E I_y} + M \frac{a}{E I_y}$$

$$\omega_x^{(1)}(A) = \omega_y^{(2)}(A) \dots -M \frac{a}{G I_x} = -2 \frac{a^3}{3 E I_y} + M \frac{a}{E I_y}$$

$$E I_y = G I_x \dots$$

$$M = 2 \frac{a^2}{6}$$

$$w_c = w_A + 2 \frac{5(2a)^4}{384EI_y} - M \frac{(2a)^2}{8EI_y}$$

$$w_c = 2 \frac{11a^4}{24EI_y}$$

 \rightarrow

$$w_c = 0,0371 \text{ m}$$